



Sequences of Earthquakes and Aseismic Slip (SEAS): From Community Code Verification to Cross-Scale Validation

Junle Jiang (The University of Oklahoma)

Brittany Erickson (U Oregon), Valère Lambert (UCSC), Taeho Kim (Stanford)

Pierre Romanet (Géoazur/Cerema), Prithvi Thakur (Brown), Mohamed Abdelmeguid (Caltech)

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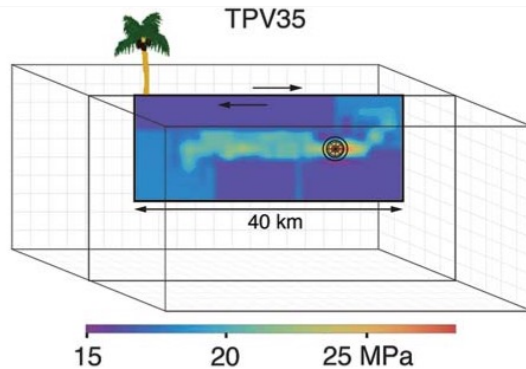




Overview

- Background & History
- Benchmark Progression & Findings
- Toward Validation

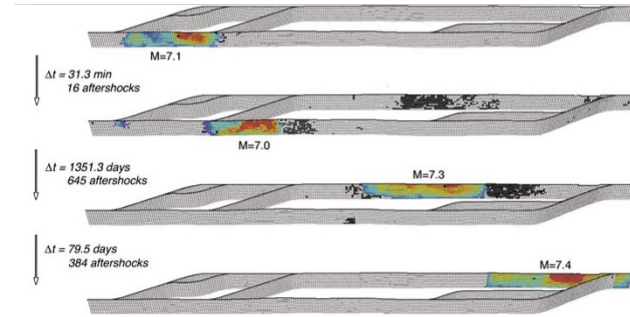
Approaches to modeling earthquakes



Harris et al., 2018

Spontaneous dynamic ruptures

- Detailed single-event earthquake ruptures
- Successful code verification and validation
- Imposed ad hoc prestress conditions and nucleation procedures



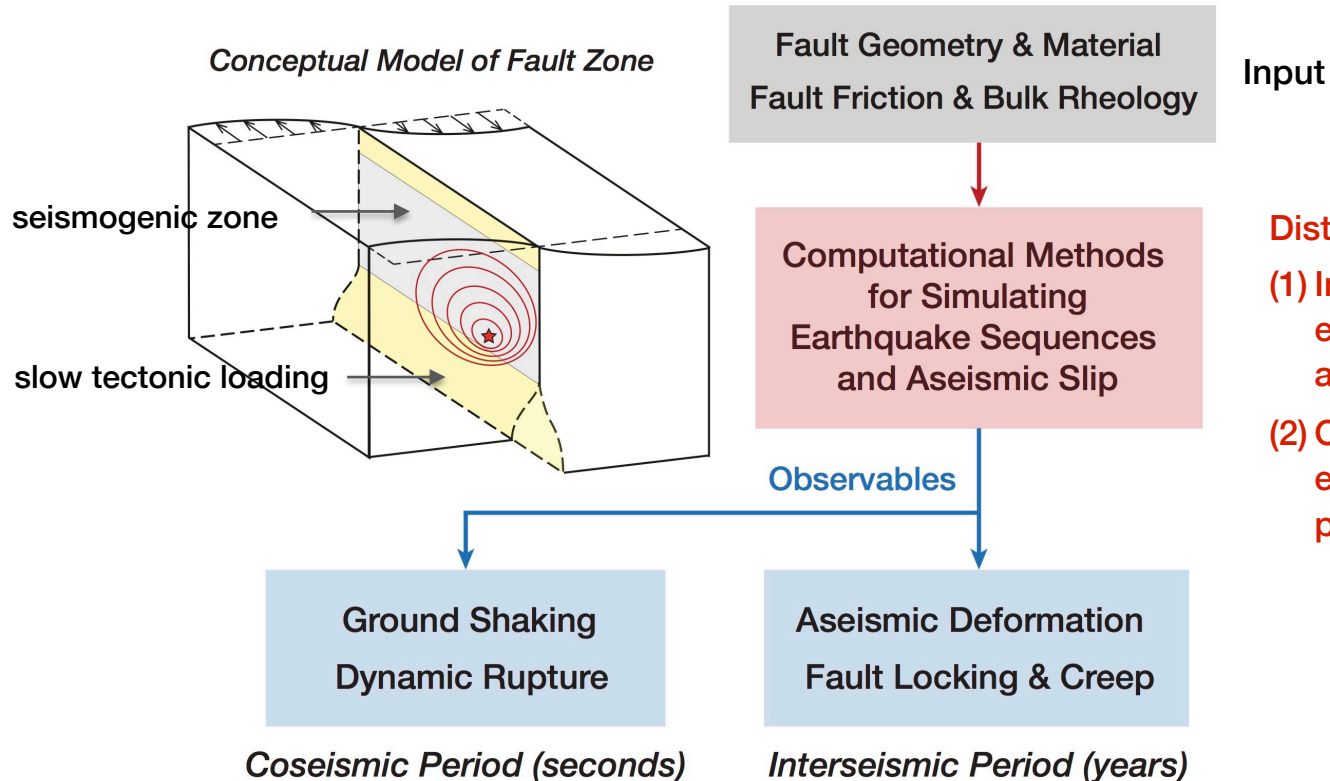
Dieterich and Richards-Dinger, 2010

Earthquake Simulators

- Able to simulate millennium-scale seismicity patterns in fault systems
- Quasi-static approximation and simplified aseismic loading to allow numerical tractability

What are SEAS models?

Sequences of Earthquakes and Aseismic Slip



Distinct features:

- (1) Interactions between earthquakes and aseismic slip
- (2) Capture detailed earthquake rupture process



Capability and complexity of SEAS models

- Transition from slow, quasi-static deformation to dynamic, wave-producing slip and to postseismic and interseismic deformation
- Interactions between seismicity and aseismic transients
- Interactions with the deeper inelastic response, fluids, and off-fault damage and healing
- Geometrical complexities and fault heterogeneity

multiple time and space scales

multiple physical factors

SEAS (“seismic cycle”) models are now prevalent in earthquake research



Outstanding questions

- Do our numerical models resolve the “true” fault behavior and its complexity?
- What model features may arise from numerical approximation and resolution issues?
- How do these physical factors influence the earthquake cycle? Do they matter?
- How to implement them with efficiency in 3D, larger-scale simulations?

Verifying different computational codes is the first critical step

Community efforts are needed to address these issues



SEAS in SCEC4/5

- SEAS was initiated in 2018 by Brittany Erickson, Junle Jiang, and Michael Barall, with much guidance from Ruth Harris, Nadia Lapusta and Eric Dunham
- Developed first SEAS benchmark problem in March 2018
- Held 1st workshop with dynamic rupture group in April 2018
- Established an online platform for model comparison, following DR group
- Valère Lambert joined leadership in 2021; Taeho/Pierre/Prithvi/Mohamed are now co-leading

Benchmark Progress

Collaboration, workshop & benchmark



Group progress over the years

- About 110 people are included on our email list
- **Six SCEC-funded workshops** since 2018
- **Eight benchmarks** (BP1–BP7) are now available online; more in development
- **Publications**
 - *Erickson, Jiang et al.*, 2020, SRL (24 coauthors) – group initiative & event size variability
 - *Jiang et al.*, 2022, JGR (19 coauthors) – 3D effects
 - *Erickson et al.*, 2023, BSSA (33 coauthors) – dynamic and dipping fault effects
 - *Lambert et al.*, 2025, JGR (24 coauthors) – fluid/friction effects on aseismic slip



Design benchmarks for code verification

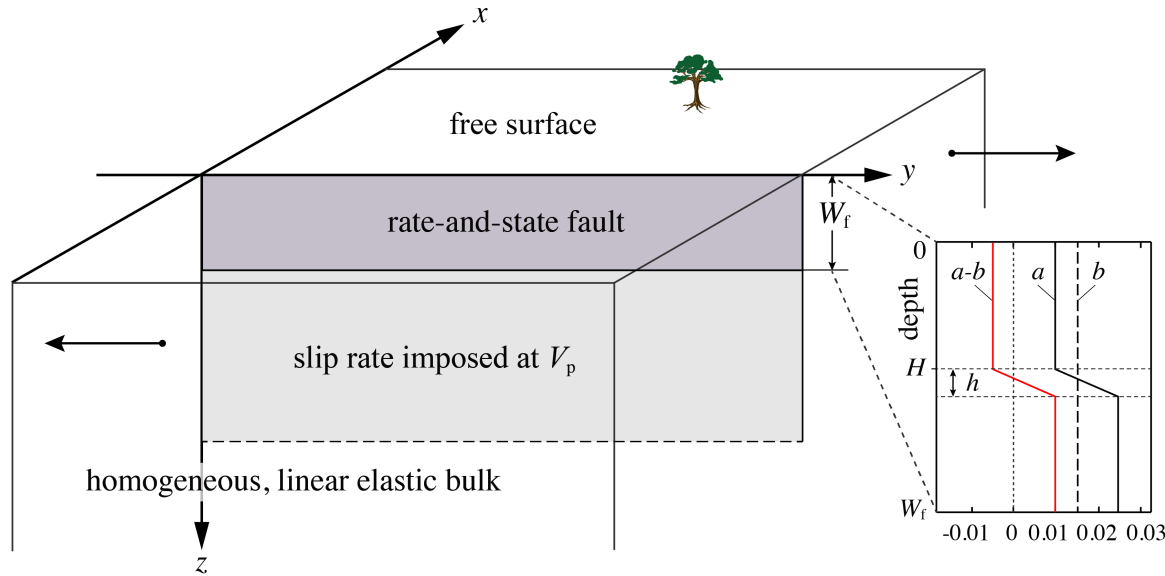
- **Guidelines**

- **Start simple** & incrementally increase model complexity
- Draw **collaboration experience** from SCEC community, especially DR group
- Building the community platform based on **existing SCEC resource** and **our needs**
- Design benchmarks that **maximize participations**

- **Tasks**

- What model features should we compare?
- How do we assess agreements and discrepancies?
- What constitute successful code verifications for SEAS models?

1st Benchmark BP1-QD

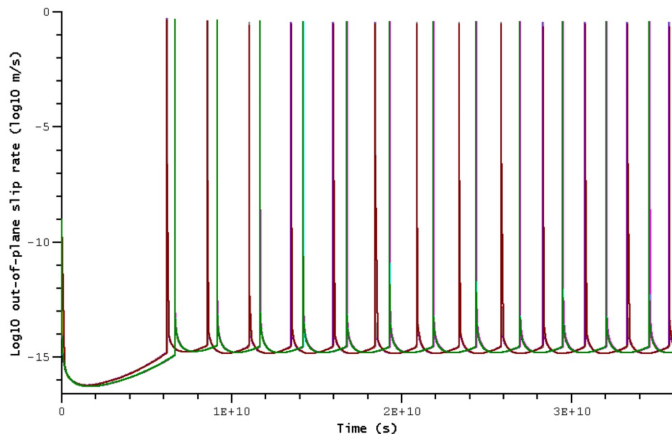


based on Rice, 1993

- **2D** anti-plane problem
- **1D** vertical strike-slip fault in a homogeneous half-space
- Rate-and-state friction with the aging evolution law
- **Quasi-dynamic** earthquakes
- Define a mathematical problem, leaving computational implementation up to modelers
- Request simulations at preferred resolutions (and more for tests)

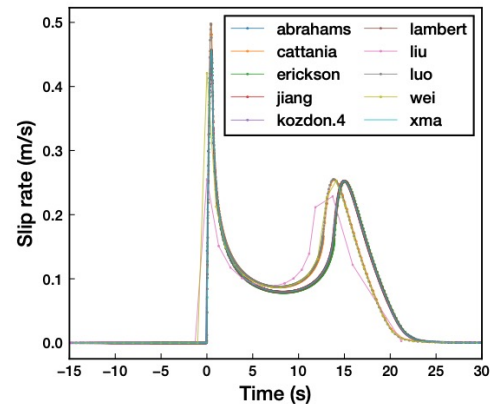
Benchmark exercises – how to compare models?

long-term evolution of slip/rate/stress

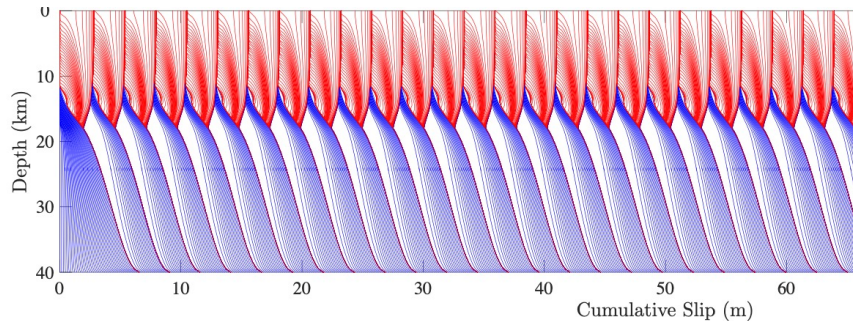


- abrahams (100 km X 80 km: Free surface outer BC)
- barbot.2 (Sylvain Barbot (Matlab))
- cattanina (Camilla Cattanina - fdra (bem))
- erickson (Brittany Erickson)
- jiang (Junle Jiang (25 m; 80 km))
- kozdon.4 (SIPG :: 160 km X 80 km :: free surface outer BC)
- lambert (Valère Lambert - 25 m, 80 km domain)
- liu.2 (Yajing Liu)
- luo (ODYN - Yingdi Luo, Ben Idini and Pablo Ampuero)
- wei (Matt Wei)
- xma (MSC-Cycle_25m_80)

coseismic
evolution of slip
rate and stress



Slip evolution
along depth





Benchmark Progression

- **BP2-QD: BP1-QD with a smaller nucleation size** – Small & large events
- **BP3-QD: 2D in-plane quasi-dynamic problem with a dipping fault** – Role of fault geometry
- **BP1-FD: Fully dynamic version of BP1-QD** – Elastodynamics vs radiation damping
- **BP4/BP5-QD: 3D quasi-dynamic problems for BP1-QD** – 3D effects in whole-/half-space
- **BP6-QD-A/S/C: 2D fluid-induced aseismic slip** – Roles of friction laws and fluids
- **BP7: 3D circular-asperity problem with different friction laws** – Repeating earthquakes

In Development:

- **BP8: 3D fluid injection** – Induced seismicity
- **BP9: 2D/3D dipping fault with depth-varying effective normal stress (SCEC/CRESCENT)**

What constitutes a successful benchmark?

Persistent Numerical Challenges

- Variable time-stepping
- Choices in computational domain size and boundary conditions
- Problem nonlinearity and round-off errors
- How to determine legitimate solution differences?
- Resolution of key spatial/temporal scales
- Numerical efficiency and computational speed

Useful Findings

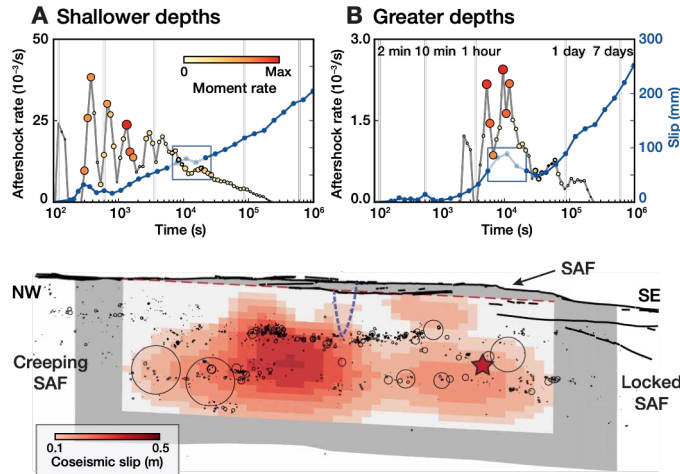
- Numerical resolutions change earthquake size distributions (Erickson, Jiang et al., 2020)
- Model-dependent loading rates affect event sequence timing, more than recurring event size (Jiang et al., 2023)
- Elastodynamics produce qualitative model differences (Erickson et al., 2023)
- A suite of quantitative error metrics (Erickson et al., 2023)
- Slip transients depend on time stepping and friction laws (Lambert et al., 2025)

Toward Validation

Some thoughts on relevance to lab friction benchmarks

Validation from Field Observations

Continuous Temporal Evolution



Parkfield
Jiang et al., 2021

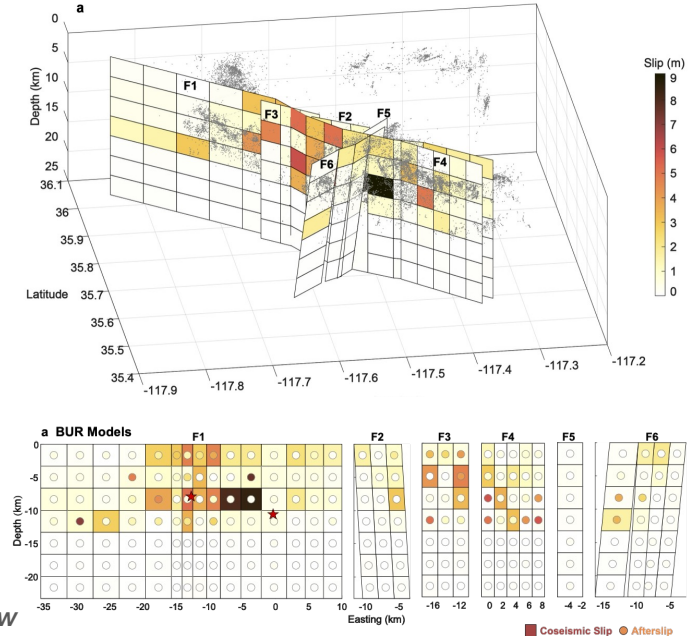
How friction changes with
loading rates and depth?

*Interplay of
Seismic-Aseismic
Fault Processes*

Ridgecrest

Zhao & Jiang, in review

Heterogeneous Spatial Pattern



How friction changes at low/high rates
and control source heterogeneity?



SEAS Models ↔ Field and Lab Observations

- Use **lab/field data** to bear on the **SEAS model design/input**
 - **Seismology/geodesy/geology**: Deformation, structure, seismicity, ground motion, ...
 - **Rock mechanics**: friction laws, bulk rheology, ...
 - The effective friction laws and frictional properties (and their spatial/temporal variations) are critical constraints in SEAS models
- **Target lab observations with SEAS model outputs?**
 - Reproduce lab data to understand model variability/discrepancy
 - Simulate lab scenarios to understand experimental/physical factors